

Servo valves Series LR Flow control - LRWA0

3/3 way servo valves for the flow control



The servo-valves LRWA0-34 and LRWA0-36 are direct driven 3/3way-valves with patented rotary slide principle and electronic closed loop slide posi-tion control. They are designed as cartridge to provide space- and cost-saving solutions especially in serial products. The servovalve cartridge has to be supplied with a controller that contains the electronic board and a connection cable. The valve controllers are adjusted to the corresponding cartridges. A correct function needs a cartridge and a controller with identical serial numbers.

GENERAL DATA

Power supply	24 VDC +/- 10%, stabilized, max. 0,8 A					
Input specified value	+/- 10V vs. 100 kohm; 0-10V vs. 100 kohm; 0-20 mA vs. 500 ohm					
Hysteresis	approx. 1% FS related to slide position					
Linearity	approx. 1% FS related to slide position					
Frequency limit (-3dB, -90°)	at +/-100% spec. val.: approx. 70 Hz; at +/- 50% spec. val.: approx. 110 Hz					
Switching time	0 to 100%: approx. 5 ms; +/- 100%: approx. 7 ms					
Temperature range	0 to 50° C					
Relative humidity of air	max. 90%					
Weight of cartridge	approx. 0,140 kg without cable					
Maximum flow rate (fully opened)	6 bar to 0 bar: 700 Nl/min (LRWA0-34) 1100 Nl/min (LRWA0-36) 6 bar to 5 bar: 450 Nl/min (LRWA0-34) 690 Nl/min (LRWA0-36)					
Medium	clean air, oiled or not oiled, 5 μm filtered					
Supply pressure	-0,9 to 10 bar					
Leakage	< 1% of maximum flow rate					
Materials	AISI 440B/1; NBR (static)					

- » Cartridge design
- » Optimal mounting options for different applications
- » Rotary slide principal, metal to metal seal
- » Space saving design at high flow rate
- » Electronic closed loop slide position control high precision
- » 3-way-function with nominal size 4 mm or 6 mm



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CODING EXAMPLE



I.

L	R W	A	0	-	3	4	-	1	-	Α	-	05
L	SERIES: L = Proportional servo va	alves										
R	TECHNOLOGY: R = rotary											
W	VERSION: W = flow control											
Α	ELECTRONICS: A = analogic											
0	MODEL: 0 = cartridge with fixatior	n slot										
3	FUNCTION: 3 = 3 way											
4	DIAMETER: 4 = 4 mm 6 = 6 mm											
1	INPUT SIGNAL: 1 = +/- 10 V 2 = 0-10 V 3= 0-20 mA											
Α	FEEDBACK SIGNAL: A = internal encoder											
05	CABLE: 05 = 0,5 m 10 = 1 m 20 = 2 m											

Example: Servo valve LRWA0 diam. 4 mm input, +/- 10V, cable 1m: LRWA0-34-1-A-10 Accessories: Fitting block with G1/4-bores, 51x40x30 mm³, material: aluminium anodised Cod. LRA0C-3





News

SERVO VALVS LRWA0 - PNEUMATIC INSTALLATION



The typical modes of installation to control a pneumatical load are the modes I and II (see table); the only difference is the relation between directions of flow and specified value. Low specified electrics values connect always ports 1 and 2, high specified values ports 2 and 3.

The modes III and IV allow flow con¬trol of two pneumatical loads with only one servo valve. The inner diameters of connected fittings and tubes should correspond to the nominal size of the valves, at least 4 mm for LRWA0-34 and 6 mm for LRWA0-36.

THE LENGTH OF THE LEADS SHOULD BE AS SHORT AS POSSIBLE, BETWEEN VALVE-OUTLET AND LOAD NORMALLY < 2 mts



E = fixation slide; F = sub-d-25 pins (male); G = cartridge fitting block

APPLICATION MODES TABLE					
MODES/Ports	1	2	3		
Mode I	Ρ	A	R		
Mode II	R	A	Р		
Mode III	A	Р	В		
Mode IV	A	R	В		

ELECTRICAL CONNECTION (Pin configuration) PIN FUNCTION NOTES 7 power supply +24 VDC 13 power supply GND 14 GND Input command signal max. voltage vs. pin 13: +/- 30 V 15 Input command signal vs. pin 14 6.8 Internal reference potential never connect to other GNDs! 1 Testpoint motor voltage +/- 10 V vs. pin 6 16 Context in feed 16 Internal reference potential 16 16 Context in feed 16					
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14 GND Input command signal max. voltage vs. pin 13: +/- 30 V 15 Input command signal vs. pin 14 6,8 Internal reference potential never connect to other GNDs! 1 Testpoint motor voltage +/- 10 V vs. pin 6	13	power supply GND			
15 Input command signal vs. pin 14 6,8 Internal reference potential never connect to other GNDs! 1 Testpoint motor voltage +/- 10 V vs. pin 6	14	GND Input command signal	max. voltage vs. pin 13: +/- 30 V		
6,8 Internal reference potential never connect to other GNDs! 1 Testpoint motor voltage +/- 10 V vs. pin 6	15	Input command signal	vs. pin 14		
1 Testpoint motor voltage +/- 10 V vs. pin 6	6,8	Internal reference potential	never connect to other GNDs!		
	1	Testpoint motor voltage	+/- 10 V vs. pin 6		
24 Testpoint side position +/- 1 V vs. pin 6	24	Testpoint slide position	+/- 1 V vs. pin 6		

The company reserves the right to vary models and dimensions without notice. Products designed for industrial applications. Sale to general public is forbidden.



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